

The `broydensolve` package

Solve a system of equations with Broyden's good method

Matthias Floré

Version 1.0 (2025/07/20)

Abstract

This package implements Broyden's good method to solve a system of equations. It is also possible to use coordinates defined by `TikZ` as known and unknown variables.

Contents

1	Usage	2
2	Motivation	2
3	Commands	2
4	Keys	3
5	Examples	4
	References	8
	Index	8
A	The source code	9
	A.1 Variables	9
	A.2 Keys	10
	A.3 Functions	10
	A.4 Document commands	13

1 Usage

The package `broydensolve` can be used by putting the following in the preamble.

```
\usepackage{broydensolve}
```

2 Motivation

To solve a system of (nonlinear) equations in a \LaTeX document, for example `Python` with the package `pythontex` or `Sage` with the package `sagetex` can be used. This could require multiple compilations or the option `shell-escape`. The package `broydensolve` is implemented with \LaTeX 3, requires 1 compilation and does not require the option `shell-escape`. Moreover, it is possible to use coordinates defined by `TikZ` as known and unknown variables.

3 Commands

`\ang` \star `\ang(<coordinate>)`
`\ang(<coordinate12
\ang(<coordinate123
\ang(<coordinate1234`

This command is defined while the command `\BroydenSolve` is executed. It can be used in the function(s) given to the key `func` and gives an angle in radians. For 1 coordinate, its expansion comes down to $\text{atan}(\langle y_1 \rangle, \langle x_1 \rangle)$, for 2 coordinates to $\text{atan}(\langle y_2 \rangle - \langle y_1 \rangle, \langle x_2 \rangle - \langle x_1 \rangle)$, for 3 coordinates to $\text{atan}(\langle y_3 \rangle - \langle y_2 \rangle, \langle x_3 \rangle - \langle x_2 \rangle) - \text{atan}(\langle y_1 \rangle - \langle y_2 \rangle, \langle x_1 \rangle - \langle x_2 \rangle)$, for 4 coordinates to $\text{atan}(\langle y_4 \rangle - \langle y_3 \rangle, \langle x_4 \rangle - \langle x_3 \rangle) - \text{atan}(\langle y_2 \rangle - \langle y_1 \rangle, \langle x_2 \rangle - \langle x_1 \rangle)$ and if this is smaller than 0 then 2π is added.

`\col` \star `\col(<coordinate123`

This command is defined while the command `\BroydenSolve` is executed. It can be used in the function(s) given to the key `func` and can be used to require that 3 points are collinear. Its expansion comes down to $\langle x_1 \rangle(\langle y_2 \rangle - \langle y_3 \rangle) + \langle x_2 \rangle(\langle y_3 \rangle - \langle y_1 \rangle) + \langle x_3 \rangle(\langle y_1 \rangle - \langle y_2 \rangle)$.

`\dis` \star `\dis(<coordinate>)`
`\dis(<coordinate12`

This command is defined while the command `\BroydenSolve` is executed. It can be used in the function(s) given to the key `func` and gives a distance. For 1 coordinate, its expansion comes down to $\sqrt{\langle x_1 \rangle^2 + \langle y_1 \rangle^2}$ and for 2 coordinates to $\sqrt{(\langle x_2 \rangle - \langle x_1 \rangle)^2 + (\langle y_2 \rangle - \langle y_1 \rangle)^2}$.

`\BroydenIterations` \star `\BroydenIterations`

This command gives the total number of iterations after the command `\BroydenSolve` is executed. This command is expandable.

\BroydenRoot * **\BroydenRoot**[$\langle iteration \rangle$]{ $\langle variable \rangle$ }

This command gives the approximation for the root for $\langle variable \rangle$ after the command **\BroydenSolve** is executed. The default value for $\langle iteration \rangle$ is the total number of iterations. This command is expandable.

\BroydenRoots * **\BroydenRoots**

This command gives the approximation(s) for the root(s) for the variable(s) as a comma separated list after the command **\BroydenSolve** is executed. This command is expandable.

\BroydenSetup **\BroydenSetup**{ $\langle keys \rangle$ }

This command sets the $\langle keys \rangle$ described in Section 4.

\BroydenSolve **\BroydenSolve**{ $\langle keys \rangle$ }

This command sets the $\langle keys \rangle$ described in Section 4 inside a group and tries to approximate the root(s) for the function(s) defined by the key **func** with respect to the variable(s) defined by the key **var** with initial value(s) defined by the key **init** using Broyden's good method, see [1]. In general, this method does *not* always converge and does *not* give an exact result. Angles and trigonometric functions are typically best in radians for this purpose. The key **stop-crit** influences when the iteration stops.

4 Keys

abs-approx-error **abs-approx-error**= $\langle value \rangle$

The $\langle value \rangle$ is used by the stopping criterion. Initially, it is 10^{-3} .

coordinates **coordinates**= $\langle boolean \rangle$

If true then the function variables are given by $\langle variable \rangle x$ and $\langle variable \rangle y$ for each $\langle variable \rangle$ in the $\langle list \rangle$ given to the key **var** until the number of variables is the same as the number of functions. The functions can contain names of coordinates defined by TikZ. For a coordinate $\langle name \rangle$, also $\langle name \rangle x$ and $\langle name \rangle y$ can be used in the functions to represent its x and y coordinate. This requires the package **tikz** and the TikZ library **calc**. After the iteration ends, TikZ coordinates are defined using the computed approximate solutions.

func **func**= $\langle list \rangle$

The comma separated $\langle list \rangle$ defines the function(s). If a function contains a **,** then this function should be placed inside braces. Also a pair of braces can be required around the whole function(s).

func-error **func-error**= $\langle value \rangle$

The $\langle value \rangle$ is used by the stopping criterion. Initially, it is 10^{-3} .

init `init=<list>`

The `<list>` defines the initial value(s) for the iteration.

iterations `iterations=<number>`

The `<number>` is used by the stopping criterion. Initially, it is 5.

rel-approx-error `rel-approx-error=<value>`

The `<value>` is used by the stopping criterion. Initially, it is 10^{-3} .

stop-crit `stop-crit=abs-approx-error`
`stop-crit=func-error`
`stop-crit=iterations`
`stop-crit=rel-approx-error`

The stopping criterion influences when the iteration stops. If the function(s) evaluate(s) to 0 then the iteration stops immediately. Otherwise, the stopping behaviors are listed below.

abs-approx-error The iteration stops if the 1-norm of the difference between the current and the previous approximation is smaller than the value given to the key **abs-approx-error**.

func-error The iteration stops if the 1-norm of the function value(s) is smaller than the value given to the key **func-error**.

iterations The iteration stops after a number of iterations determined by the key **iterations**.

rel-approx-error The iteration stops if the 1-norm of the difference between the current and the previous approximation is smaller than the product of the value given to the key **rel-approx-error** and the 1-norm of the current approximation.

Initially, the stopping criterion is **rel-approx-error**.

var `var=<list>`

The `<list>` defines the function variable(s). Only the first N elements of the `<list>` are used where N is the number of functions. The variable(s) must consist entirely of Latin letters in the range [a-zA-Z] and cannot be an existing floating point identifier. Initially, it is `x,y,z`.

5 Examples

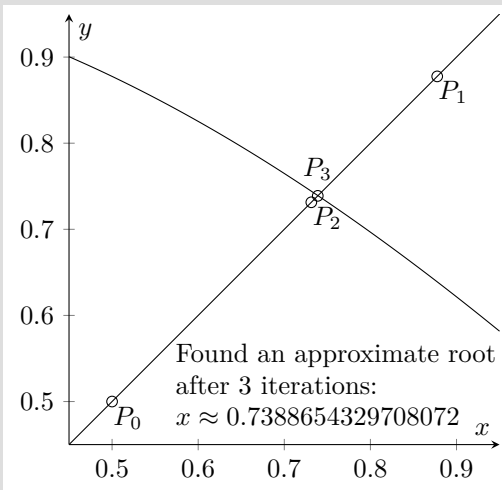
```
\BroydenSolve{
  func=x^5-x^2-1,
  init=1
}
Found an approximate root after \BroydenIterations{} iterations:\\
$x\approx\BroydenRoot{x}$
```

```
Found an approximate root after 8 iterations:
x ≈ 1.19385877093182
```

```

%\usepackage{pgfplots}
%\pgfplotsset{compat=1.18}
\begin{tikzpicture}
\BroydenSolve{
  func=x-cos(x),
  init=0.5,
  rel-approx-error=10^-1
}
\begin{axis}[
  axis equal image,
  axis lines=middle,
  xmin=0.45,
  xmax=0.95,
  ymin=0.45,
  ymax=0.95,
  xlabel=$x$,
  ylabel=$y$
]
\addplot[smooth,domain=0.45:0.95,trig format plots=rad] {cos(x)};
\addplot[smooth] {x};
\pgfplotsinvokeforeach{0,...,\BroydenIterations}{
  \draw (\BroydenRoot[#1]{x},\BroydenRoot[#1]{x}) circle[radius=2pt]
  node[xshift=\fpeval{#1=3?0:6},yshift=\fpeval{#1=3?10:-6}] {$P_{\#1}$};
}
\node[align=left] at (0.76,0.52) {Found an approximate root\\
  after \BroydenIterations{} iterations:\\
  $\approx \BroydenRoot{x}$};
\end{axis}
\end{tikzpicture}

```

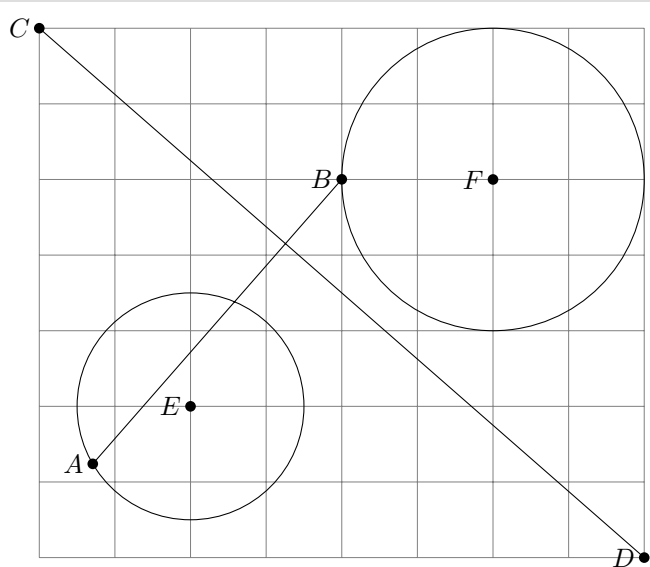


Below, we construct the points A and B so that A lies on the circle with center E , B lies on the circle with center F , $\|AB\| = 5$ and $AB \perp CD$.

```

%\usepackage{tikz}
%\usetikzlibrary{calc}
\begin{tikzpicture}
\coordinate (C) at (-2,5);
\coordinate (D) at (6,-2);
\coordinate (E) at (0,0);
\coordinate (F) at (4,3);
\BroydenSolve{
  coordinates,
  func={
    \dis(A)-1.5,
    %{\dis(A,E)-1.5},
    %Ax^2+Ay^2-1.5^2,
    {\dis(B,F)-2},
    %(Bx-Fx)^2+(By-Fy)^2-2^2,
    {\dis(A,B)-5},
    {\ang(A,B,D,C)-pi/2}
    %{\atan(Cy-Dy,Cx-Dx)-atan(By-Ay,Bx-Ax)-pi/2}
    % (Ax-Bx)*(Cx-Dx)+(Ay-By)*(Cy-Dy)
  },
  init={-1,-1,2,3},
  var={A,B}
}
\draw[help lines] (-2,-2) grid (6,5);
\draw (C)--(D) (E) circle[radius=1.5] (F) circle[radius=2] (A)--(B);
%(\BroydenRoot{Ax},\BroydenRoot{Ay})--(\BroydenRoot{Bx},\BroydenRoot{By})
\foreach\coord in {A,B,C,D,E,F}{
  \fill (\coord) circle[radius=2pt] node[left] {$\coord$};
}
\end{tikzpicture}

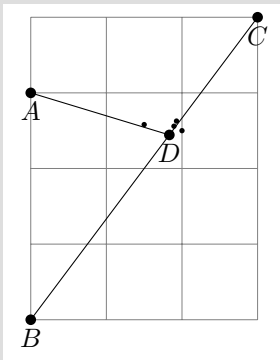
```



```

%\usepackage{tikz}
%\usetikzlibrary{calc}
\begin{tikzpicture}
\coordinate (A) at (0,3);
\coordinate (B) at (0,0);
\coordinate (C) at (3,4);
\BroydenSolve{
  coordinates,
  func={
    {\col(B,D,C)},
    {\ang(A,D,B)-70*deg}
  },
  init={2,2.5},
  var=D
}
\draw[help lines] (0,0) grid (3,4);
\draw (B)--(C) (A)--(D);
\foreach \n in {0,...,\interval{\BroydenIterations-1}}{
  \fill (\BroydenRoot[\n]{Dx},\BroydenRoot[\n]{Dy}) circle[radius=1pt];
}
\foreach \coord in {A,B,C,D}{
  \fill (\coord) circle[radius=2pt] node[below] {$\coord$};
}
\end{tikzpicture}

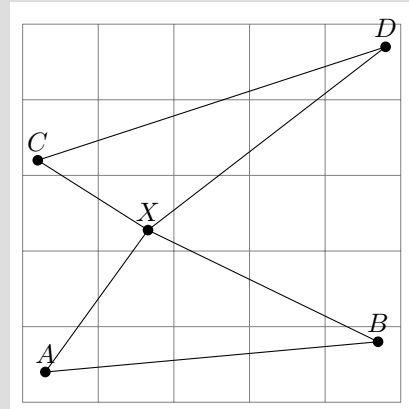
```



```

%\usepackage{tikz}
%\usetikzlibrary{calc}
\begin{tikzpicture}
\coordinate (A) at (0.3,0.4);
\coordinate (B) at (4.7,0.8);
\coordinate (C) at (0.2,3.2);
\coordinate (D) at (4.8,4.7);
\BroydenSolve{
  coordinates,
  func={
    {\ang(A,X,B)-100*deg},
    {\ang(D,X,C)-110*deg}
  },
  init={2,2},
  var=X
}
\draw[help lines] (0,0) grid (5,5);
\draw (A)--(X)--(B)--cycle (C)--(X)--(D)--cycle;
\foreach \coord in {A,B,C,D,X}{
  \fill (\coord) circle[radius=2pt]
  node[above] {\coord};
}
\end{tikzpicture}

```



References

- [1] C. G. Broyden, *A class of methods for solving nonlinear simultaneous equations*, Math. Comp. **19** (1965), 577-593.

Index

A		F	
abs-approx-error	3	func	3
\ang	2	func-error	3
B		I	
\BroydenIterations	2	init	4
\BroydenRoot	3	iterations	4
\BroydenRoots	3		
\BroydenSetup	3	R	
\BroydenSolve	3	rel-approx-error	4
C		S	
\col	2	stop-crit	4
coordinates	3		
D		V	
\dis	2	var	4

A The source code

```
%% broydensolve.sty
%% Copyright 2025 Matthias Floré
%
% This work may be distributed and/or modified under the
% conditions of the LaTeX Project Public License, either version 1.3c
% of this license or (at your option) any later version.
% The latest version of this license is in
%   http://www.latex-project.org/lppl.txt
% and version 1.3c or later is part of all distributions of LaTeX
% version 2005/12/01 or later.
%
% This work has the LPPL maintenance status `maintained'.
%
% The Current Maintainer of this work is Matthias Floré.
%
% This work consists of the files broydensolve-doc.pdf, broydensolve.sty,
% broydensolve-doc.tex and README.md.
\NeedsTeXFormat{LaTeX2e}
\ProvidesExplPackage{broydensolve}{2025/07/20}{1.0}{Solve a system of equations with Broyden's good method}
```

A.1 Variables

```
\bool_new:N \l__broydensolve_do_bool

\clist_new:N \g__broydensolve_roots_clist

\fp_new:N \l__broydensolve_aux_fp
\fp_new:N \g__broydensolve_coord_x_fp
\fp_new:N \g__broydensolve_coord_y_fp
\fp_new:N \l__broydensolve_det_fp
\fp_new:N \l__broydensolve_norm_h_fp
\fp_new:N \l__broydensolve_norm_x_fp

\int_new:N \g__broydensolve_iterations_int
\int_new:N \l__broydensolve_N_int
```

```

\seq_new:N \l__broydensolve_coordinates_seq
\seq_new:N \l__broydensolve_coords_seq
\seq_new:N \l__broydensolve_func_seq
\seq_new:N \l__broydensolve_init_seq
\seq_new:N \l__broydensolve_var_seq
\seq_new:N \l__broydensolve_var_N_seq

```

```

\tl_new:N \l__broydensolve_func_tl
\tl_new:N \l__broydensolve_name_tl

```

A.2 Keys

```

\keys_define:nn { broydensolve }
{
  abs-approx-error .fp_set:N = \l__broydensolve_abs_approx_error_fp ,
  abs-approx-error .initial:n = 10-3 ,
  coordinates .bool_set:N = \l__broydensolve_coordinates_bool ,
  func .tl_set:N = \l__broydensolve_funcs_tl ,
  func-error .fp_set:N = \l__broydensolve_func_error_fp ,
  func-error .initial:n = 10-3 ,
  init .code:n = \exp_args:NNe \seq_set_from_clist:Nn \l__broydensolve_init_seq {#1} ,
  iterations .int_set:N = \l__broydensolve_iterations_int ,
  iterations .initial:n = 5 ,
  rel-approx-error .fp_set:N = \l__broydensolve_rel_approx_error_fp ,
  rel-approx-error .initial:n = 10-3 ,
  stop-crit .str_set_e:N = \l__broydensolve_stop_crit_str ,
  stop-crit .initial:n = rel-approx-error ,
  var .code:n = \exp_args:NNe \seq_set_from_clist:Nn \l__broydensolve_var_seq {#1} ,
  var .initial:n = { x , y , z }
}

```

A.3 Functions

```

\cs_new:Npn \__broydensolve_add:n #1
{ ( #1 < 0 ? ( #1 + 2 * pi ) : ( #1 ) ) }

\cs_new_protected:Npn \__broydensolve_add_name:N #1

```

```

{
  \tl_if_empty:nF {#1}
  {
    \cs_if_exist:cTF { __fp_parse_word_#1:N }
    { \tl_build_put_right:Nn \l__broydensolve_func_tl {#1} }
    {
      \bool_if:NTF \l__broydensolve_coordinates_bool
      {
        \tl_set:Ne \l__broydensolve_name_tl { \tl_range:nnn {#1} { 1 } { -2 } }
        \seq_if_in:NVTF \l__broydensolve_coordinates_seq \l__broydensolve_name_tl
        { \tl_build_put_right:Nn \l__broydensolve_func_tl { \cs:w l__broydensolve_var_#1_fp \cs_end: } }
        {
          \seq_if_in:NVF \l__broydensolve_coords_seq \l__broydensolve_name_tl
          {
            \path let \p { l__broydensolve_coord } = ( \l__broydensolve_name_tl ) in
            [
              / utils / exec =
              {
                \fp_gset:Nn \g__broydensolve_coord_x_fp
                {
                  ( \pgf@yy * \x { l__broydensolve_coord } - \pgf@yx * \y { l__broydensolve_coord } )
                  / \l__broydensolve_det_fp
                }
                \fp_gset:Nn \g__broydensolve_coord_y_fp
                {
                  ( \pgf@xx * \y { l__broydensolve_coord } - \pgf@xy * \x { l__broydensolve_coord } )
                  / \l__broydensolve_det_fp
                }
              }
            ] ;
            \fp_zero_new:c { l__broydensolve_coord_\l__broydensolve_name_tl x_fp }
            \fp_zero_new:c { l__broydensolve_coord_\l__broydensolve_name_tl y_fp }
            \fp_set_eq:cN { l__broydensolve_coord_\l__broydensolve_name_tl x_fp } \g__broydensolve_coord_x_fp
            \fp_set_eq:cN { l__broydensolve_coord_\l__broydensolve_name_tl y_fp } \g__broydensolve_coord_y_fp
            \seq_put_right:NV \l__broydensolve_coords_seq \l__broydensolve_name_tl
          }
        }
      }
      \tl_build_put_right:Ne \l__broydensolve_func_tl { \fp_use:c { l__broydensolve_coord_#1_fp } }
    }
  }
}

```

```

        { \tl_build_put_right:Nn \l__broydensolve_func_tl { \cs:w l__broydensolve_var_#1_fp \cs_end: } }
      }
    }

\cs_new:Npn \__broydensolve_atan:nnn #1#2#3
{ atan ( \clist_item:nn {#1} {#2} y - \clist_item:nn {#1} {#3} y , \clist_item:nn {#1} {#2} x - \clist_item:nn {#1} {#3} x ) }

\cs_new_protected:Npn \__broydensolve_init:nn #1#2
{
  \fp_gzero_new:c { g__broydensolve_x_0_#2_fp }
  \fp_gset:cn { g__broydensolve_x_0_#2_fp } {#1}
  \fp_zero_new:c { l__broydensolve_var_#2_fp }
  \fp_set:cn { l__broydensolve_var_#2_fp } {#1}
}

\cs_new_protected:Npn \__broydensolve_stop_crit:
{
  \fp_set:Nn \l__broydensolve_aux_fp { abs ( \seq_use:Nn \l__broydensolve_func_seq { } ) + abs ( } ) }
  \fp_compare:nNnTF { \l__broydensolve_aux_fp } > { 0 }
  {
    \str_case:VnF \l__broydensolve_stop_crit_str
    {
      { abs-approx-error }
      {
        \int_if_zero:nF { \g__broydensolve_iterations_int }
        {
          \fp_zero:N \l__broydensolve_norm_h_fp
          \int_step_inline:nn { \l__broydensolve_N_int }
          { \fp_add:Nn \l__broydensolve_norm_h_fp { abs ( \cs:w l__broydensolve_h_##1_fp \cs_end: ) } }
          \bool_set:Nn \l__broydensolve_do_bool
          { \fp_compare_p:nNn { \l__broydensolve_norm_h_fp } < { \l__broydensolve_abs_approx_error_fp } }
        }
      }
    }
  }
  { func-error }
  {
    \bool_set:Nn \l__broydensolve_do_bool
    { \fp_compare_p:nNn { \l__broydensolve_aux_fp } < { \l__broydensolve_func_error_fp } }
  }
}

```

```

    }
    { iterations }
    {
      \bool_set:Nn \l__broydensolve_do_bool
      { \int_compare_p:nNn { \g__broydensolve_iterations_int } = { \l__broydensolve_iterations_int } }
    }
    { rel-approx-error }
    {
      \int_if_zero:nF { \g__broydensolve_iterations_int }
      {
        \fp_zero:N \l__broydensolve_norm_h_fp
        \fp_zero:N \l__broydensolve_norm_x_fp
        \seq_map_indexed_inline:Nn \l__broydensolve_var_N_seq
        {
          \fp_add:Nn \l__broydensolve_norm_h_fp { abs ( \cs:w l__broydensolve_h_##1_fp \cs_end: ) }
          \fp_add:Nn \l__broydensolve_norm_x_fp { abs ( \cs:w l__broydensolve_var_##2_fp \cs_end: ) }
        }
        \bool_set:Nn \l__broydensolve_do_bool
        {
          \fp_compare_p:nNn
            { \l__broydensolve_norm_h_fp } < { \l__broydensolve_rel_approx_error_fp * \l__broydensolve_norm_x_fp }
        }
      }
    }
  }
  { \PackageError { broydensolve } { Wrong~value~for~key~stop-crit } {} }
}
{ \bool_set_true:N \l__broydensolve_do_bool }
}

```

A.4 Document commands

```

\NewExpandableDocumentCommand \BroydenIterations {}
{ \int_use:N \g__broydensolve_iterations_int }

\NewExpandableDocumentCommand \BroydenRoot { 0 { \g__broydensolve_iterations_int } m }
{ \fp_use:c { g__broydensolve_x_\int_eval:n {#1}_#2_fp } }

```

```

\NewExpandableDocumentCommand \BroydenRoots {}
{ \g__broydensolve_roots_clist }

\NewDocumentCommand \BroydenSetup { m }
{ \keys_set:nn { broydensolve } {#1} }

\NewDocumentCommand \BroydenSolve { m }
{
  \group_begin:
  \keys_set:nn { broydensolve } {#1}
  \DeclareExpandableDocumentCommand \ang { r () }
  {
    \__broydensolve_add:n
    {
      \int_case:nnF { \clist_count:n {##1} }
      {
        { 1 } { atan ( \clist_item:nn {##1} { 1 } y , \clist_item:nn {##1} { 1 } x ) }
        { 2 } { \__broydensolve_atan:nnn {##1} { 2 } { 1 } }
        { 3 } { \__broydensolve_atan:nnn {##1} { 3 } { 2 } - \__broydensolve_atan:nnn {##1} { 1 } { 2 } }
        { 4 } { \__broydensolve_atan:nnn {##1} { 4 } { 3 } - \__broydensolve_atan:nnn {##1} { 2 } { 1 } }
      }
      { \ang {} }
    }
  }
}
\DeclareExpandableDocumentCommand \col { r () }
{
  \int_compare:nNnTF { \clist_count:n {##1} } = { 3 }
  {
    \clist_item:nn {##1} { 1 } x * ( \clist_item:nn {##1} { 2 } y - \clist_item:nn {##1} { 3 } y )
    + \clist_item:nn {##1} { 2 } x * ( \clist_item:nn {##1} { 3 } y - \clist_item:nn {##1} { 1 } y )
    + \clist_item:nn {##1} { 3 } x * ( \clist_item:nn {##1} { 1 } y - \clist_item:nn {##1} { 2 } y )
  }
  { \col {} }
}
\DeclareExpandableDocumentCommand \dis { r () }
{
  \int_case:nnF { \clist_count:n {##1} }
  {

```

```

{ 1 } { sqrt ( \clist_item:nn {##1} { 1 } x ^ 2 + \clist_item:nn {##1} { 1 } y ^ 2 ) }
{ 2 }
{
  sqrt
  (
    ( \clist_item:nn {##1} { 2 } x - \clist_item:nn {##1} { 1 } x ) ^ 2
    + ( \clist_item:nn {##1} { 2 } y - \clist_item:nn {##1} { 1 } y ) ^ 2
  )
}
{ \dis {} }
}
\int_set:Nn \l__broydensolve_N_int { \clist_count:e { \l__broydensolve_funcs_tl } }
\bool_if:NTF \l__broydensolve_coordinates_bool
{
  \seq_map_indexed_inline:Nn \l__broydensolve_var_seq
  {
    \seq_put_right:Nn \l__broydensolve_var_N_seq { ##2 x }
    \seq_put_right:Nn \l__broydensolve_var_N_seq { ##2 y }
    \seq_put_right:Nn \l__broydensolve_coordinates_seq {##2}
    \int_compare:nNnT {##1} = { \l__broydensolve_N_int / 2 }
    { \seq_map_break: }
  }
}
\fp_set:Nn \l__broydensolve_det_fp { \pgf@yy * \pgf@xx - \pgf@yx * \pgf@xy }
}
{
  \seq_map_indexed_inline:Nn \l__broydensolve_var_seq
  {
    \seq_put_right:Nn \l__broydensolve_var_N_seq {##2}
    \int_compare:nNnT {##1} = { \l__broydensolve_N_int }
    { \seq_map_break: }
  }
}
}
\exp_args:Ne \clist_map_inline:nn { \l__broydensolve_funcs_tl }
{
  \tl_build_begin:N \l__broydensolve_func_tl
  \tl_build_begin:N \l__broydensolve_name_tl
  \tl_map_inline:nn {##1}
  {

```

```

\bool_lazy_and:nnTF
{ \bool_lazy_or_p:nn { \int_compare_p:nNn { `####1 } < { `a } } { \int_compare_p:nNn { `z } < { `####1 } } }
{ \bool_lazy_or_p:nn { \int_compare_p:nNn { `####1 } < { `A } } { \int_compare_p:nNn { `Z } < { `####1 } } }
{
  \tl_build_end:N \l__broydensolve_name_tl
  \exp_args:NV \__broydensolve_add_name:N \l__broydensolve_name_tl
  \tl_build_begin:N \l__broydensolve_name_tl
  \tl_build_put_right:Nn \l__broydensolve_func_tl {####1}
}
{ \tl_build_put_right:Nn \l__broydensolve_name_tl {####1} }
}
\tl_build_end:N \l__broydensolve_name_tl
\exp_args:NV \__broydensolve_add_name:N \l__broydensolve_name_tl
\tl_build_end:N \l__broydensolve_func_tl
\seq_put_right:NV \l__broydensolve_func_seq \l__broydensolve_func_tl
}
\seq_map_pairwise_function:NNN \l__broydensolve_init_seq \l__broydensolve_var_N_seq \__broydensolve_init:nn
\int_step_inline:nn { \l__broydensolve_N_int }
{
  \int_step_inline:nn { \l__broydensolve_N_int }
  { \fp_zero_new:c { l__broydensolve_B_##1_####1_fp } }
  %set B to the identity matrix
  \fp_set:cn { l__broydensolve_B_##1_##1_fp } { 1 }
  \fp_zero_new:c { l__broydensolve_w_##1_fp }
  \fp_zero_new:c { l__broydensolve_h_##1_fp }
  \fp_zero_new:c { l__broydensolve_aux_##1_fp }
  \fp_zero_new:c { l__broydensolve_auxi_##1_fp }
}
\int_gzero:N \g__broydensolve_iterations_int
\__broydensolve_stop_crit:
\bool_until_do:Nn \l__broydensolve_do_bool
{
  %set w=-f(x)
  \seq_map_indexed_inline:Nn \l__broydensolve_func_seq
  { \fp_set:cn { l__broydensolve_w_##1_fp } { - (##2) } }
  %set h=-B*f(x)=B*w
  \int_step_inline:nn { \l__broydensolve_N_int }
  {
    \fp_zero:c { l__broydensolve_h_##1_fp }

```



```

\int_step_inline:nn { \l__broydensolve_N_int }
{
  \fp_add:cn { l__broydensolve_h_##1_fp }
  { \cs:w l__broydensolve_B_##1_####1_fp \cs_end: * \cs:w l__broydensolve_w_####1_fp \cs_end: }
}
}
%set the variable(s) to x+h
\seq_map_indexed_inline:Nn \l__broydensolve_var_N_seq
{ \fp_add:cn { l__broydensolve_var_##2_fp } { \cs:w l__broydensolve_h_##1_fp \cs_end: } }
%add f(x+h) to w so that w=f(x+h)-f(x)
\seq_map_indexed_inline:Nn \l__broydensolve_func_seq
{ \fp_add:cn { l__broydensolve_w_##1_fp } {##2} }
%update B
\int_step_inline:nn { \l__broydensolve_N_int }
{
  \fp_zero:c { l__broydensolve_aux_##1_fp }
  \int_step_inline:nn { \l__broydensolve_N_int }
  {
    \fp_add:cn { l__broydensolve_aux_##1_fp }
    { \cs:w l__broydensolve_B_##1_####1_fp \cs_end: * \cs:w l__broydensolve_w_####1_fp \cs_end: }
  }
}
\fp_zero:N \l__broydensolve_aux_fp
\int_step_inline:nn { \l__broydensolve_N_int }
{
  \fp_add:Nn \l__broydensolve_aux_fp { \cs:w l__broydensolve_h_##1_fp \cs_end: * \cs:w l__broydensolve_aux_##1_fp \cs_end: }
  \fp_sub:cn { l__broydensolve_aux_##1_fp } { \cs:w l__broydensolve_h_##1_fp \cs_end: }
}
\int_step_inline:nn { \l__broydensolve_N_int }
{
  \fp_zero:c { l__broydensolve_auxi_##1_fp }
  \int_step_inline:nn { \l__broydensolve_N_int }
  {
    \fp_add:cn { l__broydensolve_auxi_##1_fp }
    { \cs:w l__broydensolve_h_####1_fp \cs_end: * \cs:w l__broydensolve_B_####1_##1_fp \cs_end: }
  }
}
\int_step_inline:nn { \l__broydensolve_N_int }
{

```

```

\int_step_inline:nn { \l__broydensolve_N_int }
{
  \fp_sub:cn { l__broydensolve_B_##1_####1_fp }
  {
    \cs:w l__broydensolve_aux_##1_fp \cs_end: * \cs:w l__broydensolve_auxi_####1_fp \cs_end:
    / \l__broydensolve_aux_fp
  }
}
}
\int_gincr:N \g__broydensolve_iterations_int
\seq_map_inline:Nn \l__broydensolve_var_N_seq
{
  \fp_gzero_new:c { g__broydensolve_x \int_use:N \g__broydensolve_iterations_int _##1_fp }
  \fp_gset_eq:cc { g__broydensolve_x \int_use:N \g__broydensolve_iterations_int _##1_fp } { l__broydensolve_var_##1_fp }
}
\__broydensolve_stop_crit:
}
\clist_gclear:N \g__broydensolve_roots_clist
\seq_map_inline:Nn \l__broydensolve_var_N_seq
{ \clist_gput_right:Ne \g__broydensolve_roots_clist { \BroydenRoot {##1} } }
\bool_if:NT \l__broydensolve_coordinates_bool
{
  \seq_map_inline:Nn \l__broydensolve_coordinates_seq
  { \coordinate (##1) at ( \BroydenRoot { ##1 x } , \BroydenRoot { ##1 y } ) ; }
}
\group_end:
}

\endinput

```